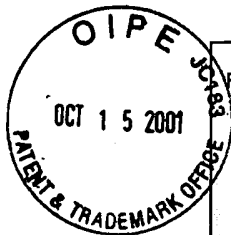




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Form PTO-1449		Docket No.: 39262/256238		Application No.: 09/827,252	
INFORMATION DISCLOSURE CITATION IN AN APPLICATION (Use several sheets if necessary)		Applicant: J. Charles Taylor, et al.			
		Filing Date: April 5, 2001		Group Art Unit 3731	
U.S. PATENT DOCUMENTS					
Examiner Initial	Patent Number	Date	Patentee	Class	Subclass
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Examiner: <u>Jack R. Zhe</u>			Date Considered: <u>10/15/02</u>		
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Form PTO-1449

Docket No.:

39262/256238

Application No.

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Applicant:

J. Charles Taylor, et al.

Filing Date:

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Group Art Unit

3731

INFORMATION DISCLOSURE
CITATION

IN AN APPLICATION

(Use several sheets if necessary)

U.S. PATENT DOCUMENTS (continued)

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<i>CA</i>	6,030,386	02/2000	Taylor, et al.		

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	WO 92/17313	10/1992	WIPO			
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Examiner:

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Date Considered:

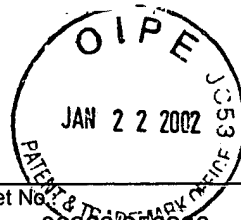
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	Ji, Z., "Dynamics Decomposition for Stewart Platforms", <i>Journal of Mechanical Design</i> , vol. 116, Mar. 1994, pp. 67-69.		
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	Liu, K., Lewis, F.L., Fitzgerald, M., "Solution Of Nonlinear Kinematics Of A Parallel-Link Constrained Stewart Platform Manipulator", <i>Circuits Systems Signal Process</i> , vol. 13, No. 2-3, 1994, pp. 167-183.		
JA	Monticelli Spinelli® External Fixation System, cover and pp. 1-28.		
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	Sreenivasan, S.V., Waldron, K.J., "Closed-Form Direct Displacement Analysis Of A 6-6 Stewart Platform", <i>Mech. Mach. Theory</i> , vol. 29, No. 6, 1994, pp. 855-864.		
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JA	Techniques In Orthopaedics, <i>Basic Ilizarov Techniques</i> , vol. 5, No. 4, Dec. 1990, 4 pages.		
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	Wen, F., Liang, C., "Displacement Analysis Of The 6-6 Stewart Platform Mechanisms", <i>Mech. Mach. Theory</i> , vol. 29, No. 4, 1994, pp. 547-557.		
	Wohlhart, K., "Displacement Analysis Of The General Spherical Stewart Platform", <i>Mech. Mach. Theory</i> , vol. 29, No. 4, 1994, pp. 581-589.		
	Zhang, C., Song, S., "Forward Position Analysis Of Nearly General Stewart Platforms", <i>Journal of Mechanical Design</i> , vol. 116, pp. 54-60, Mar. 1994.		
Examiner:	Date Considered:		
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		Filing Date: April 5, 2001	Group Art Unit 3731
OTHER MATERIAL			
Examiner Initial	Including Author, Title, Date, Pertinent Pages, Etc.		
	Zhuang, H., Roth, Z.S., "Method For Kinematic Calibration Of Stewart Platforms", <i>Journal Of Robotic Systems</i> , 10(3), 1993, pp. 391-405.		
	NO COPY NOT CONSIDERED		
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Examiner:			Date Considered: 11/15/02
EXAMINER: Initial if citation considered, whether or not citation is in conformance with MPEP § 609; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to the applicant.			



Sheet 1 of 3

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		Applicant: J. Charles Taylor, et al.				
		Filing Date: April 5, 2001		Group Art Unit 3731		
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		2,391,537	12/1945	Anderson		
		2,487,989	11/1949	Sherburne		
		3,176,805	04/1965	Gandy		
		3,727,610	04/1973	Riniker		
		3,941,123	03/1976	Volkov et al.		
		3,977,397	08/1976	Kalnberz et al.		
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		4,628,922	12/1986	Dewar		
		4,662,365	05/1987	Gotzen et al.		
		4,768,524	09/1988	Hardy		
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		5,179,525	01/1993	Griffis et al.		
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Sheet 2 of 3

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		Applicant: J. Charles Taylor, et al.					
		Filing Date: April 5, 2001			Group Art Unit 3731		
U.S. PATENT DOCUMENTS (continued)							
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JA		5,209,750	05/1993	Stef			
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		6,030,386	02/2000	Taylor, et al.			
	NON U.S. DOCUMENTS						
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JA		0 589 565	03/1994	EPO			
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		108119	07/1917	UK			
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	WO 92/17313	10/1992	WIPO				
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Examiner: <i>Jacobieha</i>				Date Considered: 1/15/02			
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